



**MACHINE FOR MAKING A NON-WOVEN MATERIAL  
BY AEROLOGICAL MEANS  
USING A DISPERSIVE AIR FLOW**

5           This invention concerns the field of manufacturing non-woven materials by aerological means which goes by the technical name "airlay." More specifically, it concerns an improvement of a machine for airlaying a non-woven material that permits a significant increase in the production speed with no detriment to quality of the non-woven material produced.

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          The "airlay" technique basically consists of dispersing individual fibers in a chamber and projecting them onto a moving receptive surface by means of a high-speed air flow; said receptive surface is permeable to air and allows said non-woven material to be formed and conveyed. The term "non-woven" in this text designates the web of fibers  
15       formed by the "airlay" technique, even when this web has not undergone any special bonding technique.

          Such an "airlay" technique is known particularly from documents US 4 097 965, EP 0 093 585 and FR 2 824 082.

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          In these three documents, the means of producing an air flow inside the dispersion chamber that allows the fibers to disperse within the chamber and be projected onto the forming and conveying surface consist particularly of vacuum means located below the forming and conveying surface of the non-woven material which is permeable to air.

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          In document US 4 097 965, the wall downstream from the dispersion chamber is a plate whose lower edge is applied to the surface of the non-woven material coming out of said chamber, with the vacuum tank mounted over the whole surface, which extends perpendicular to the lower edge of the wall upstream and the lower edge of the wall  
30       downstream from the dispersion chamber. In this text, the terms "downstream" and

“upstream” are defined in relation to the direction in which the forming and conveying surface of the non-woven material moves.

5 According to the applicant, contact between the lower edge of the downstream wall of the dispersion chamber and the surface fibers of the non-woven material generates friction that can cause irregularities in the non-woven material, especially if the forming and conveying surface of the non-woven material moves at high speed.

10 In document EP 0 093 585, there is a transverse cylinder at the output of the dispersion chamber that is set in rotation in the direction in which the non-woven material moves. The rotation of this cylinder, which constitutes in some way the lower edge of the wall downstream from the dispersion chamber, makes it possible to limit the friction and hence accompany the surface fibers of the non-woven material when they come out of the dispersion chamber. However, according to the applicant, if you increase the speed at which the non-woven material moves on the forming and conveying surface so that it is correlative to the speed of rotation of the transverse cylinder, parasitic air flows are produced that interfere with the homogeneity of the non-woven material when it passes under the transverse cylinder.

20 In document FR 2 824 082, the lower part of the front wall of the dispersion chamber is porous, and the profile of said lower part is preferably curved approximately like the arc of a circle. This prevents the production of parasitic air flows caused by the rapid rotation of the transverse cylinder. However, in operation, the thin microperforated sheet metal that constitutes the lower part of the wall downstream from the dispersion chamber exerts a low compressive force on the non-woven material that slightly compresses it. This prevents the vacuum flow produced by the vacuum tank from causing an incoming air flow that would penetrate inside of the dispersion chamber, passing between the lower edge of the downstream wall and the upper end of the forming and conveying surface of the non-woven material; such an air flow is detrimental to the quality of said non-woven material.

However, according to the applicant, this contact between the thin microperforated sheet metal and the surface fibers of the non-woven coming out of the dispersion chamber causes friction that can deform the non-woven material and produce irregularities on it, and even more so the higher the speed at which the forming and  
5 conveying surface of the non-woven material moves.

In document FR 2 824 082, the lower porous part of the front wall of the dispersion chamber can also be comprised of a porous rotary cylinder, particularly a microperforated cylinder. This embodiment makes it possible to avoid friction when the  
10 cylinder is driven at a peripheral speed equal to the speed at which the forming and conveying surface of the non-woven material moves. However, some parasitic air play may subsist, even if it is not as much as in document EP 0 093 585.

The purpose of this invention is to propose an airlay machine for a non-woven  
15 material that eliminates the disadvantages of the known machines mentioned above.

This purpose is achieved by the machine in the invention which, as is known particularly from US 4 097 965, has:

- 20 - a forming and conveying surface for the non-woven material that is permeable to air,
- a dispersion chamber surmounting the forming and conveying surface,
- means of feeding the fibers intended to form the non-woven material into the dispersion chamber,
- 25 - means, particularly vacuum means, located under the forming and conveying surface of the non-woven material that can produce an air flow within the dispersion chamber that makes it possible to disperse the fibers within the chamber and project them onto the forming and conveying surface.

Characteristically, according to the invention, said vacuum means can produce a  
30 vacuum in a zone – called the vacuum zone – of the forming and conveying surface of the non-woven material that extends under the dispersion chamber and downstream from

it, with a reduction in the vacuum speed between the upstream and downstream parts of said zone.

5 Thus, because the vacuum is located not only under the dispersion chamber, but also downstream from it, with a vacuum speed that decreases from upstream to downstream, the vacuum flow is controlled perfectly, including any parasitic flows, so as to obtain a perfectly regular non-woven material, even if the forming and conveying surface for said non-woven material moves at high speed.

10 In another embodiment, the wall downstream from the dispersion chamber is a plate whose lower edge delimits, along with the upper end of the forming and conveying surface of the non-woven material, a space for passage whose height is higher than the thickness of the non-woven material coming out of the dispersion chamber.

15 Thus, in this particular arrangement, there is no longer any piece that comes in contact with the non-woven material when it comes out of the dispersion chamber.

In another variation, the wall downstream from the dispersion chamber is a rotary cylinder, preferably porous or perforated. This variation is of particular interest when it  
20 is necessary to compress the web of fibers to evacuate the air contained between them.

In another variation, the vacuum means are composed of a single vacuum tank in which the vacuum conditions decrease from the upstream to the downstream parts of the vacuum zone.  
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In another variation, the vacuum means are composed of a multi-stage vacuum tank, with each stage having distinct vacuum conditions.

30 Preferably, in this latter embodiment, a first stage having the highest vacuum speed  $V_1$  is located under the dispersion chamber in the primary section of the vacuum zone extending up to a distance  $d$  perpendicular to the lower edge of the wall downstream

from the dispersion chamber and at least one second stage, developing a vacuum speed  $V_2$  slower than  $V_1$ , extends downstream from the first stage over a secondary section of the vacuum zone. Thus, in this particular configuration, the vacuum speed is not uniform over the whole length of the vacuum chamber; the vacuum speed is the fastest in the primary section, located upstream from the vacuum zone, which corresponds to the first vacuum stage, while it is lower in the secondary section of the vacuum zone that extends beyond the first stage, specifically over the distance  $d$ .

In one embodiment, in the secondary section of the vacuum zone, the machine has only one second stage in which the vacuum speed gradually decreases from the upstream to the downstream part of said secondary section.

In one embodiment, in the secondary section of the vacuum zone, the machine has a plurality  $N$  of successive second stages. The vacuum speed can be constant in each of these  $N$  second stages or can gradually decrease from the upstream to the downstream part of said stage.

The characteristics and advantages of the invention will be clearer after reading the following description of different variations of an airlaying machine for non-wovens. This description is given as a non-limiting example and refers to the attached drawings in which:

- Figures 1 to 4 are very schematic representations illustrating the operating principle of the machine in four variations, namely:

- A first variation (Figure 1) in which the secondary section of the vacuum zone develops a vacuum speed that continually decreases from upstream to downstream,
- A second variation (Figure 2) in which the secondary section of the vacuum zone has five stages in which the vacuum speed is constant.

- A third variation (Figure 3) in which the secondary section of the vacuum zone has five stages in which the vacuum speed itself decreases and,
- A fourth variation (Figure 4) in which the secondary section of the vacuum zone has five vacuum stages, some having a constant vacuum speed and others having a decreasing vacuum speed.

- Figure 5 is a simplified cross-sectional view of a machine for airlaying a non-woven material whose operation is based on the second variation illustrated in Figure 2.

In a way that is known, a machine for airlaying non-woven material has a conveyor using a porous conveyor belt 1 that is mounted under tension on drive rollers. When operating, the upper end 1a of this conveyor belt 1, which in the examples illustrated is approximately horizontal, is driven at a constant predetermined speed in the direction of conveyance indicated by arrow F. This upper end 1a of the conveyor belt 1 forms a surface permeable to air that makes it possible both to form and to transport the non-woven material.

This machine also has a chamber 2 for dispersion of the fibers, which surmounts the upper end 1a of the conveyor belt 1 and which extends over the whole width of this upper end 1a. This dispersion chamber 2 has an upstream wall 3 and a downstream wall 4, which extend transversely in the direction F in which the conveyor belt 1 moves, and two longitudinal walls connecting the two walls upstream 3 and downstream 4, which longitudinal walls extend parallel to the direction of movement F.

The lower edges of the upstream and longitudinal walls 3 (not shown) are flush with the upper end 1a of the conveyor belt 1, and are potentially equipped with a gasket supported on said upper end 1a.

Under the upper end 1a, there is a vacuum tank which can, potentially with other means, produce an air flow 7 inside the dispersion chamber 2 symbolized by arrows that makes it possible to disperse the fibers (not shown) inside said chamber 2 and project

them onto the upper end 1a. The cylinder 8, called the dispersing cylinder, supplies the dispersion chamber 2 with fibers.

The tank 6 (or vacuum box) extends, under the upper end 1a, over a vacuum zone 9, which zone 9 occupies, in width, at least the width of the dispersion chamber 2 and in length, a distance D that is longer than the length L of the dispersion chamber 2. The vacuum conditions used in the tank 6 are such that the vacuum speed, measured in the tank 6, in the downstream part 9a of the vacuum zone 9 is lower than the vacuum speed in the upstream part 9b of the vacuum zone 9.

In the examples that will be described below, the vacuum tank 6 is a multi-stage tank, having a first stage 10 which extends under a section called the primary section of the vacuum zone 9, and this primary section 9c extends, in length, over a distance l which is less than the length L of the vacuum zone 9 surmounted by the dispersion chamber 2.

In other words, referring to Figure 5, this primary section 9c extends from approximately the lower edge 11 of the wall 3 upstream from the dispersion chamber 2 (or slightly downstream from it) to a distance d perpendicular to the lower edge 12 of the wall downstream 4 from the dispersion chamber 2. In this primary section 9c of the vacuum zone 9, the vacuum speed V1 is generated at the first stage 10 and is uniform over the whole length l of said stage 10.

In the first embodiment, illustrated in Figure 1, the vacuum tank 6 has a second stage 13 that covers the second section 9d of the vacuum zone, which goes beyond the primary section 9c described above. In this second stage 13 of the tank 6, the conditions used are such that the vacuum speed gradually decreases over the whole length of the second section 9d from its input to its output, as illustrated in Figure 1 by the continued decrease in arrows V2, symbolizing the vacuum speed in said secondary section 9d.

In the second example illustrated in Figure 2, the secondary section 9d is divided into five subsections 9d<sub>1</sub>, 9d<sub>2</sub>, 9d<sub>3</sub>, 9d<sub>4</sub>, 9d<sub>5</sub>, from upstream to downstream of said

secondary section 9d. In each subsection, the vacuum speed V3 is constant. This speed V3 decreases from one section to another from the upstream to the downstream part of said secondary section 9d. One stage 14 to 18 of the vacuum tank 6 corresponds to each subsection 9d<sub>1</sub> to 9d<sub>5</sub>.

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The third example illustrated in Figure 3 shows the five stages 14 to 18 of the vacuum tank 6 that correspond to secondary vacuum section 9d and hence to five subsections 9'd<sub>1</sub> to 9'd<sub>5</sub>. In each subsection, the vacuum speed V4 is not constant, but gradually decreases over the length of each stage 14 to 18 from the upstream to the downstream part of each subsection, as can be clearly seen by examining Figure 3.

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The fourth example of embodiment, which is illustrated in Figure 4, is a combination of the second and third examples described above, with the vacuum speed V5 gradually decreasing in certain stages 14, 16 and 18, while it stays constant in certain others 15, 17.

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The operation of the machine in this invention will now be described more specifically in relation to the second example illustrated by Figures 2 and 5.

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For the sake of simplification, in Figure 5, the vacuum tank 6 has only three stages, namely the first stage 10, which corresponds to the primary section 9c of the vacuum zone 9, and two successive second stages 14 and 15, which correspond to subsections 9d<sub>1</sub> and 9d<sub>2</sub> of the secondary section 9d of the vacuum zone 9.

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The fibers that are fed to the interior of the dispersion chamber 2, on the periphery of the dispersing cylinder 8 are detached from the fittings 8a of this cylinder by the action of the air flow produced inside the dispersion chamber 11 and potentially by other means. The fibers are ejected individually inside the dispersion chamber 2, are dispersed by the air flow over the whole horizontal section of said chamber 2 and are projected over the upper end 1a of the conveyor belt 1. Due to the accumulation of fibers on the upper end 1a when the conveyor belt 1 moves, a non-woven material 13 is formed that is taken to

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the outside of the dispersion chamber 2, passing at right angles to the wall 4 downstream from said chamber 2, which in the example illustrated is a plate. The spacing between the lower edge 12 of said downstream wall 4 and the upper end 1a is set so that it is greater than the thickness of the non-woven material formed in the dispersion chamber 2,  
5 which is where it is when it comes out of said chamber 2.

The air flow that moves the fibers inside the dispersion chamber 2 is produced particularly by the vacuum tank 6, more specifically by the vacuum generated by the part of the vacuum section 9 that is at right angles to the dispersion chamber 2. Other  
10 additional means could be used, for example an injection of air at the upper part of the dispersion chamber 2, to help detach the fibers from the cylinder 8.

Given that the vacuum speed  $V_1$  generated at the first stage 10 of the vacuum tank 6 is the highest, the fibers in the dispersion chamber 2 have a tendency to  
15 concentrate on the upper end 1a of the primary vacuum section 9c, so that the non-woven material 13 is quasi-formed in its final configuration when it comes out of the first stage 10 of the vacuum tank 6.

Beyond that, the non-woven material is taken over in some way by the second  
20 stage 14 of the vacuum tank 6 in which the vacuum speed  $V_2$  is lower than the speed  $V_1$  of the first stage. This takeover occurs when the non-woven material 13 is still inside the dispersion chamber 2 over the distance  $d$ , right when the non-woven material 13 has come out of the dispersion chamber 2. This takeover, which continues in the second stage 14 of the vacuum tank 6, does not allow any disturbances caused by the non-woven  
25 material passing under the downstream rise 4 of the dispersion chamber 2, since approximately the same system is observed for the air flow on both sides of this downstream rise 4. Due to the vacuum produced beyond the dispersion chamber under the upper end 1a, no parasitic air flows are seen entering into the vacuum chamber in the space left free between the non-woven material 13 and the lower edge 12 of the  
30 downstream rise 4 or at least no lifting detrimental to the fibers is seen.

This is also true when the lower edge of the downstream wall is not the edge of a fixed plate but a revolving element, for example a perforated transverse cylinder which compresses the non-woven material coming out of the dispersion chamber 2.

5           When it comes out of subsection 9d<sub>1</sub>, from secondary section 9d of the vacuum zone 9, the non-woven material is then taken over by the vacuum produced by the next second stage 15 of the vacuum tank 6, whose vacuum speed V<sub>3</sub> is less than the vacuum speed V<sub>2</sub> of the second stage 14. This takeover is done successively with the other second stages 16 to 18 until there is no longer any vacuum at all beyond the tank 6. This  
10 gradual reduction (in stages in this example) in the vacuum in the secondary zone 9d allows the fibers of the non-woven material 13 to relax gradually due to the effect of said vacuum. This is what makes it possible to obtain the results wanted, namely the production of a very homogeneous non-woven material under good industrial conditions at high speed.

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          It is understood that the different parameters, which consist of the choice of vacuum speeds V<sub>1</sub>, V<sub>2</sub>, .., the length D of the vacuum zone compared to the length L of the dispersion chamber, the distance d, the number of stages of the vacuum tank, the option of keeping the vacuum speed constant or having it decrease in all or some of the  
20 second stages—all these parameters are determined individually, depending on the other operating conditions, which are the type and length of the fibers, the grams per square meter desired for the non-woven material and the speed F at which the conveyor belt moves.

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          In one embodiment, which is not exhaustive, the vacuum speed V<sub>1</sub> in the primary section 9c of the vacuum zone 9 was around 30 to 90 m/s. Preferably, the vacuum speeds of the five second stages found in the secondary section 9d of the vacuum zone 9 were respectively equal to or on the order of 0.8 V, 0.6 V, 0.4 V and 0.2 V, it being known that V is the speed of the first stage the furthest upstream and had a value itself less than V<sub>1</sub>,  
30 for example 0.8 V<sub>1</sub>. To do this, the first stage at speed V<sub>1</sub> of the vacuum tank was

equipped with its own fan, while a second fan for the five second stages made it possible to obtain this decreasing vacuum speed using perforated sheets of metal.

However, this invention is not limited to the embodiments which have been  
5 described as non-exhaustive examples. In particular, it would be possible to have, above the upper end 1a of the conveyor belt 1, some compression rollers designed to accompany the movement of the fibers of the non-woven material, which compression rollers would be located advantageously at right angles to the interface between two successive subsections, or even at right angles to the interface between the primary  
10 section 9c and the secondary section 9d of the vacuum zone.

All suitable means may be used to obtain the vacuum speeds in the vacuum tank, whether from a single fan or a plurality of fans, and from additional elements that could reduce the vacuum speed, potentially in a gradual way, from the upstream to the  
15 downstream part of the vacuum zone.